

# Mario Baggetta

DIME - Dept. of Mechanical, Energy, Management and Transportation Engineering, University of Genova, Italy

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in mario-baggetta-96b1a713a

Born 30 August 1992

### **WORK EXPERIENCE**

Nov. 2020 - present

# Research Assistant - PhD candidate

University of Genova, DIME, Genova, Italy

- · Research Topics:
  - -Underactuated robotic hands
  - -Analysis/design/optimization of compliant mechanisms and flexible components
- -Structural optimizations
- -Applications: human-like compliant joints, variable stiffness actuators
- Teaching Activity:
- -Member of the examination board for "Mechanics of Machines" (BSc in Mechanical Engineering) and "Technical Drawing" (BSc in Naval Architecture and Marine Engineering, BSc in Nautical Engineering)

# Jun. 2019 - Oct. 2020 Research Fellow

University of Genova, DIME, Genova, Italy

- · Research Topics:
  - -Multi-Flexible body dynamics
  - -Non-linear FEA
  - -Mechatronics Systems control
- · Consulting Activity for Ansaldo Energia:
- -Factory 4.0
- -Advanced simulation of assembly operations
- -FEA simulation of heavy lifting operations

## **EDUCATION**

Nov. 2020 - present

## PhD in Mechanical Engineering

University of Genova, DIME, Genova, Italy · Supervisors: Prof. Giovanni Berselli

Sept. 2016 - Mar. 2019

# MSc in Mechanical Engineering

University of Genova, DIME, Genova, Italy

• Scored: 109/110

Sept. 2011 - Dec. 2016

# BSc in Mechanical Engineering

University of Genova, DIME, Genova, Italy

· Scored: 90/110

# PERSONAL SKILLS

Languages

• Italian: Mother tongue

· English: Professional Knowledge

TECHNICAL SKILLS .

**Operating System** 

· Windows: Office Package, Adobe Illustrator, Latex

## **Programming Languages**

- Matlab
- Labview

## Computer Aided Design

- PTC Creo
- Solidworks (Certified Associate C-8KSNEK4ETG)
- NX

### Multibody Dynamics

- RecurDyn
- Simulink

### Finite Element Analysis

ANSYS Workbench

#### **PROJECTS**

Jun. 2019 – present

## Lighthouse Plant

Ansaldo Energia, Genova, Italy

- Main activities: Advanced simulation of assembly and manipulation operations in Factory 4.0.
- Budget: 14 m€

### **REVIEWER ACTIVITY**

Reviewer for the journals:

Transactions on Mechatronics (IEEE)

Reviewer for the conferences:

 IEEE BioRob - International Conference on Biomedical Robotics and Biomechatronics

### **PUBLICATIONS**

# Journal Papers:

- **J1:** Bilancia, P., **Baggetta, M.**, Hao, G., Berselli, G. "A variable section beams based Bi-BCM formulation for the kinetostatic analysis of cross-axis flexural pivots". International Journal of Mechanical Sciences, (UNDER REVIEW)
- **J2:** Bilancia, P., **Baggetta, M.**, Berselli, G., Bruzzone, L., Fanghella, P. "Design of a Bio-Inspired Contact-Aided Compliant Wrist". Robotics and Computer-Integrated Manufacturing, 2021, 67, 102028.
- **J3:** Bruzzone, L., **Baggetta, M.**, Nodehi, S.E., Bilancia, P., Fanghella, P. "Functional design of a hybrid leg-wheel-track ground mobile robot". Machines, 2021, 9(1), pp.1-11, 10.
- **J4:** Bruzzone, L., Fanghella, P., **Baggetta, M.**. "Experimental assessment of fractional-order pdd1/2 control of a brushless motor with inertial load". Actuators, 2020, 9(1), 13.

# Posters & Workshops:

**PW1: Baggetta, M.**, Bilancia, P., Berselli, G., Bruzzone, L., Fanghella, P., (2020). CAE-based design of a cable driven human-like robotic wrist. International CAE Conference.